

# Bayesian Models in Machine Learning

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# Frequentist vs. Bayesian

- Frequentist point of view:
  - Probability is the frequency of an event occurring in a large (infinite) number of trials
  - E.g. When flipping a coin many times, what is the proportion of heads?
- Bayesian
  - Inferring probabilities for events that have never occurred or believes which are not directly observed
  - Prior beliefs are specified in terms of prior probabilities
  - Taking into account uncertainty (posterior distribution) of the estimated parameters or hidden variables in our probabilistic model.

# Coin flipping example

$$P(\text{head}|\mu) = \mu \quad P(\text{tail}|\mu) = 1 - \mu$$

$$\mathbf{x} = [x_1, x_2, x_3, \dots x_N] = [\text{tail}, \text{head}, \text{head}, \dots \text{tail}]$$

- Lets flip the coin  $N = 1000$  times getting  $H = 750$  heads and  $T = 250$  tails.
- What is  $\mu$ ? Intuitive (and also ML) estimate is  $750 / 1000 = 0.75$ .
- Given some  $\mu$ , we can calculate probability (likelihood) of  $X$

$$P(\mathbf{x}|\mu) = \prod_i P(x_i|\mu) = \mu^H(1 - \mu)^T$$

- Now lets express our *ignorant* prior belief about  $\mu$  as:

$$p(\mu) = \mathcal{U}(0,1)$$

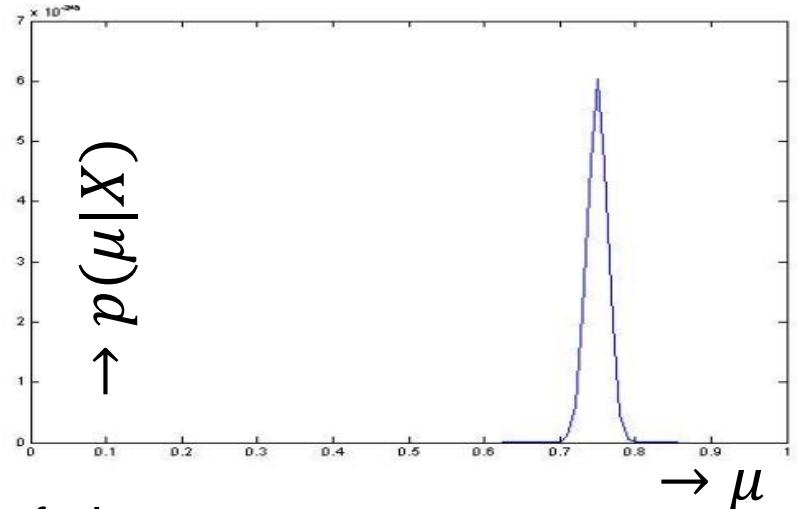
Then using Bayes rule, we obtain probability density function for  $\mu$  :

$$p(\mu|\mathbf{x}) = \frac{P(\mathbf{x}|\mu)p(\mu)}{P(\mathbf{x})} = \frac{\prod_i P(x_i|\mu) \cdot 1}{P(\mathbf{x})} \propto \mu^H(1 - \mu)^T$$

# Coin flipping example (cont.)

$$N = 1000, H = 750, T = 250$$

$$p(\mu|\mathbf{x}) \propto \mu^H(1-\mu)^T$$



- Posterior distribution is our *new belief* about  $\mu$
- Flipping the coin once more, what is the probability of head?

$$\begin{aligned} p(\text{head}|\mathbf{x}) &= \int p(\text{head}, \mu|\mathbf{x}) d\mu = \int P(\text{head}|\mu, \mathbf{x}) p(\mu|\mathbf{x}) d\mu \\ &= (H + 1)/(N + 2) = 751/1002 = 0.7495 \end{aligned}$$

- Note that we never computed value of  $\mu$
- Rule of succession used by Pierre-Simon Laplace to estimate that the probability of sun rising tomorrow is  $(5000*365.25+1)/(5000*365.25+2)$

# Distributions from our example

- Likelihood of observed data  $P(X|\mu)$  given a parametric model of probability distribution
  - Bernoulli distribution with parameter  $\mu$
- Prior on the parameters of the model  $p(\mu)$ 
  - Uniform prior as a special case of Beta distribution
- Posterior distribution of model parameters given an observed data

$$p(\mu|X) = \frac{P(X|\mu)p(\mu)}{P(X)}$$

- Posterior predictive distribution of a new observation give prior (training) observations

$$p(head|X) = \int P(head|\mu)p(\mu|X)d\mu$$

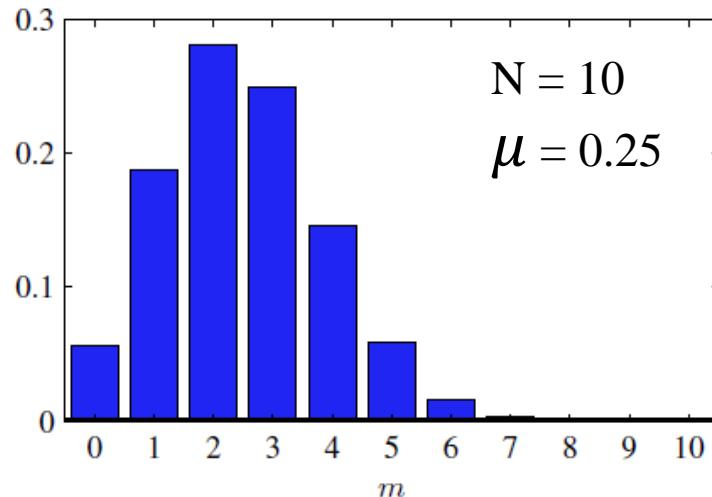
# Bernoulli and Binomial distributions

$$\text{Bern}(x|\mu) = \mu^x(1 - \mu)^{1-x}$$

- The “coin flipping” distribution is **Bernoulli distribution**
- Flipping the coin once, what is the probability of  $x = 1$  (head) or  $x = 0$  (tail)

$$\text{Bin}(m|N, \mu) = \binom{N}{m} \mu^m (1 - \mu)^{N-m}$$

- Related **binomial distribution** is also described by single probability  $\mu$
- How many heads do I get if I flip the coin  $N$  times?

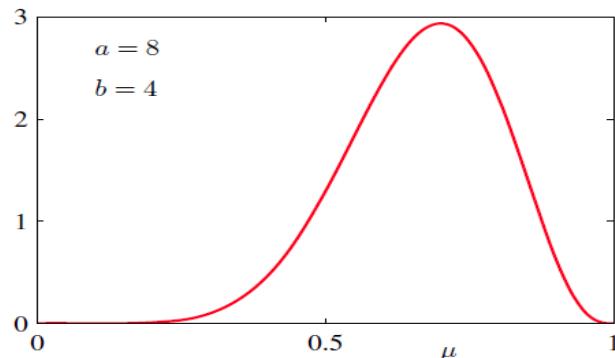
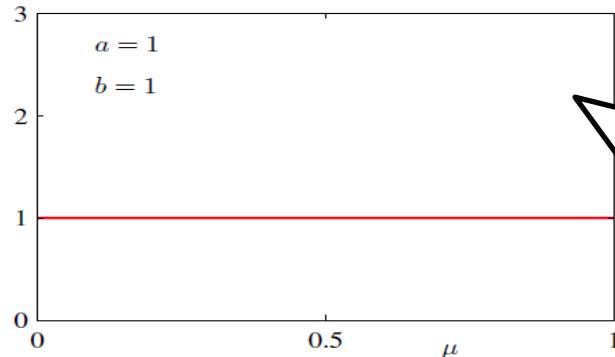
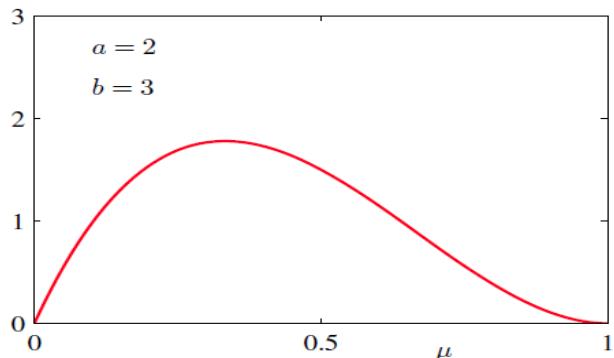
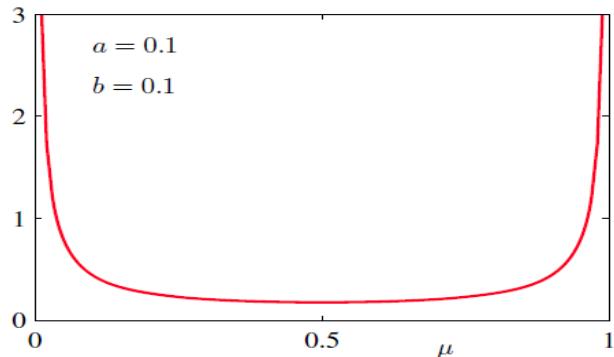


# Beta distribution

$$\text{Beta}(\mu|a, b) = \frac{\Gamma(a + b)}{\Gamma(a)\Gamma(b)} \mu^{a-1} (1 - \mu)^{b-1}$$

Normalizing constant

- **Beta distribution** has “similar” form as Bern or Bin, but it is now function of  $\mu$
- Continuous distribution for  $\mu$  over the interval (0,1)
- Can be used to express our prior beliefs about the Bernoulli dist. parameter  $\mu$



Uniform distribution over  $\mu$  as was the prior in our coin flipping example

# Beta as a conjugate prior

$$\mathbf{x} = [x_1, x_2, x_3, \dots, x_N] = [1, 0, 0, 1, \dots, 0]$$

$$P(\mathbf{x}|\mu) = \prod_i Bern(x_i|\mu) = \prod_i \mu^{x_i}(1-\mu)^{1-x_i} = \mu^H(1-\mu)^T$$

$$\text{Beta}(\mu|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \mu^{a-1}(1-\mu)^{b-1}$$

$$\begin{aligned} p(\mu|\mathbf{x}) &= \frac{P(\mathbf{x}|\mu)p(\mu)}{P(\mathbf{x})} \propto \mu^H(1-\mu)^T \mu^{a-1}(1-\mu)^{b-1} \\ &= \mu^{H+a-1}(1-\mu)^{T+b-1} \propto \text{Beta}(\mu|H+a, T+b) \end{aligned}$$

Sufficient statistics

- Using **Beta as a prior for Bernoulli parameter  $\mu$**  results in **Beta posterior distribution** → **Beta is conjugate prior to Bernoulli**
- $a - 1$  and  $b - 1$  can be seen as a prior counts of heads and tails.
- Continuous distribution of  $\mu$  over the interval  $(0,1)$
- Beta distribution can be used to express our prior beliefs about the Bernoulli distributions parameter  $\mu$

# Categorical and Multinomial distribution

$$\mathbf{x} = [0, 0, 1, 0, 0, 0]$$

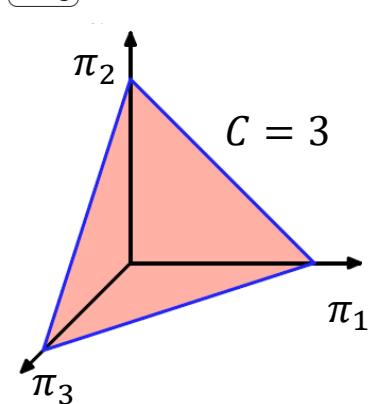
One-hot encoding of a discrete event (⚀ on a dice)

$$\boldsymbol{\pi} = [\pi_1, \pi_2, \dots, \pi_C]$$

Probabilities of the events  
(eg.  $\left[\frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}\right]$  for fair dice)

$$\text{Cat}(\mathbf{x}|\boldsymbol{\pi}) = \prod_c \pi_c^{x_c}$$

$\sum_c \pi_c = 1 \rightarrow \boldsymbol{\pi}$  is a point on a simplex



- **Categorical distribution** simply “returns” the probability of a given event  $\mathbf{x}$
- Sample from the distribution is the event (or its one-hot encoding)

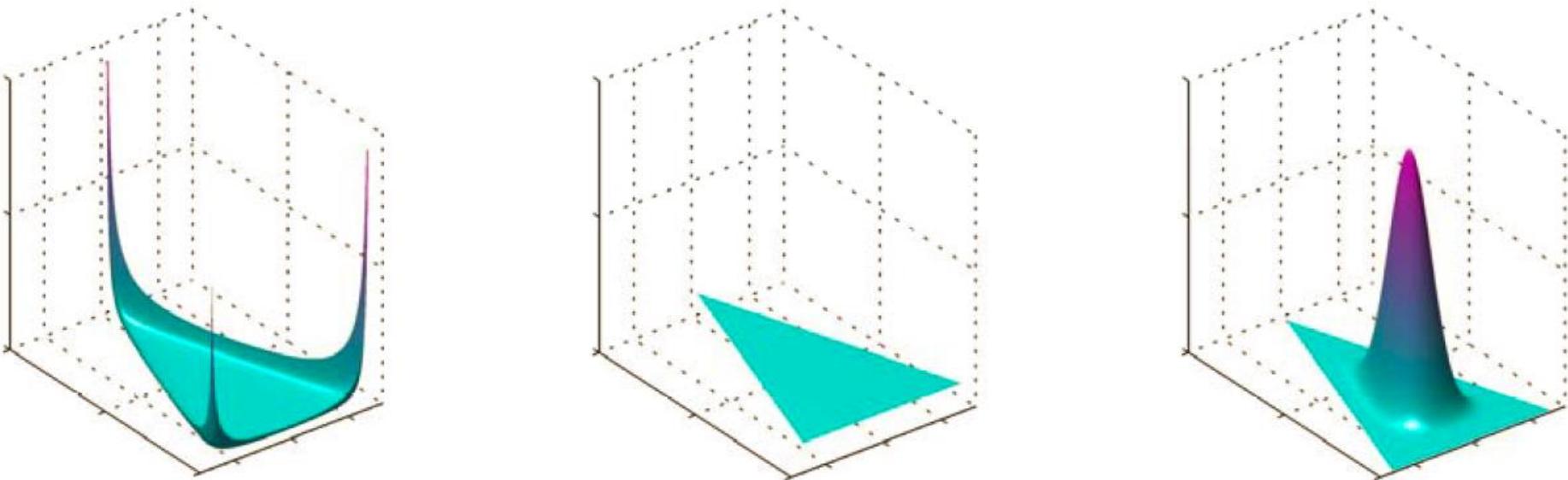
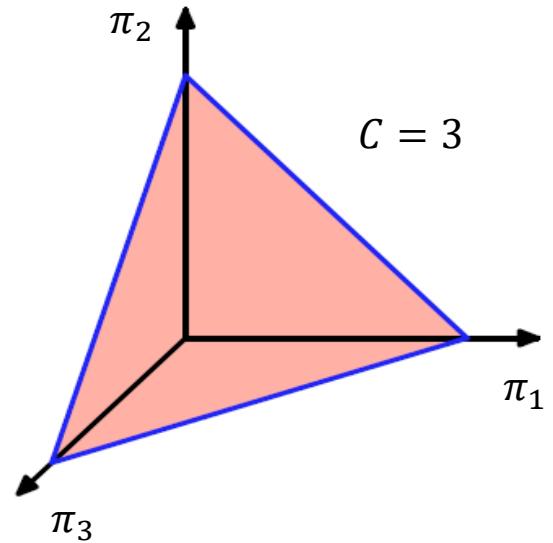
$$\text{Mult}(m_1, m_2, \dots, m_C | \boldsymbol{\pi}, N) = \binom{N}{m_1 m_2 \dots m_C} \prod_c \pi_c^{m_c}$$

- **Multinomial distribution** is also described by single probability vector  $\boldsymbol{\pi}$
- How many ones, twos, threes, ... do I get if I throw the dice  $N$  times?
- Sample from the distribution is vector of numbers (e.g. 11x one, 8x two, ...)

# Dirichlet distribution

$$\text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}) = \frac{\Gamma(\sum_c \alpha_c)}{\Gamma(\alpha_1) \dots \Gamma(\alpha_C)} \prod_{c=1}^C \pi_c^{\alpha_c - 1}$$

- **Dirichlet distribution** is continuous distribution over the points  $\boldsymbol{\pi}$  on a K dimensional simplex.
- Can be used to express our prior beliefs about the categorical distribution parameter  $\boldsymbol{\pi}$



# Dirichlet as a conjugate prior

$$P(\mathbf{X}|\boldsymbol{\pi}) = \prod_n \text{Cat}(\mathbf{x}_n|\boldsymbol{\pi}) = \prod_n \prod_c \pi_c^{x_{cn}} = \prod_c \pi_c^{m_c}$$

$$\text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}) = \frac{\Gamma(\sum_c \alpha_c)}{\Gamma(\alpha_1) \dots \Gamma(\alpha_C)} \prod_{c=1} \pi_c^{\alpha_c - 1}$$

number of training observations of category  $c$

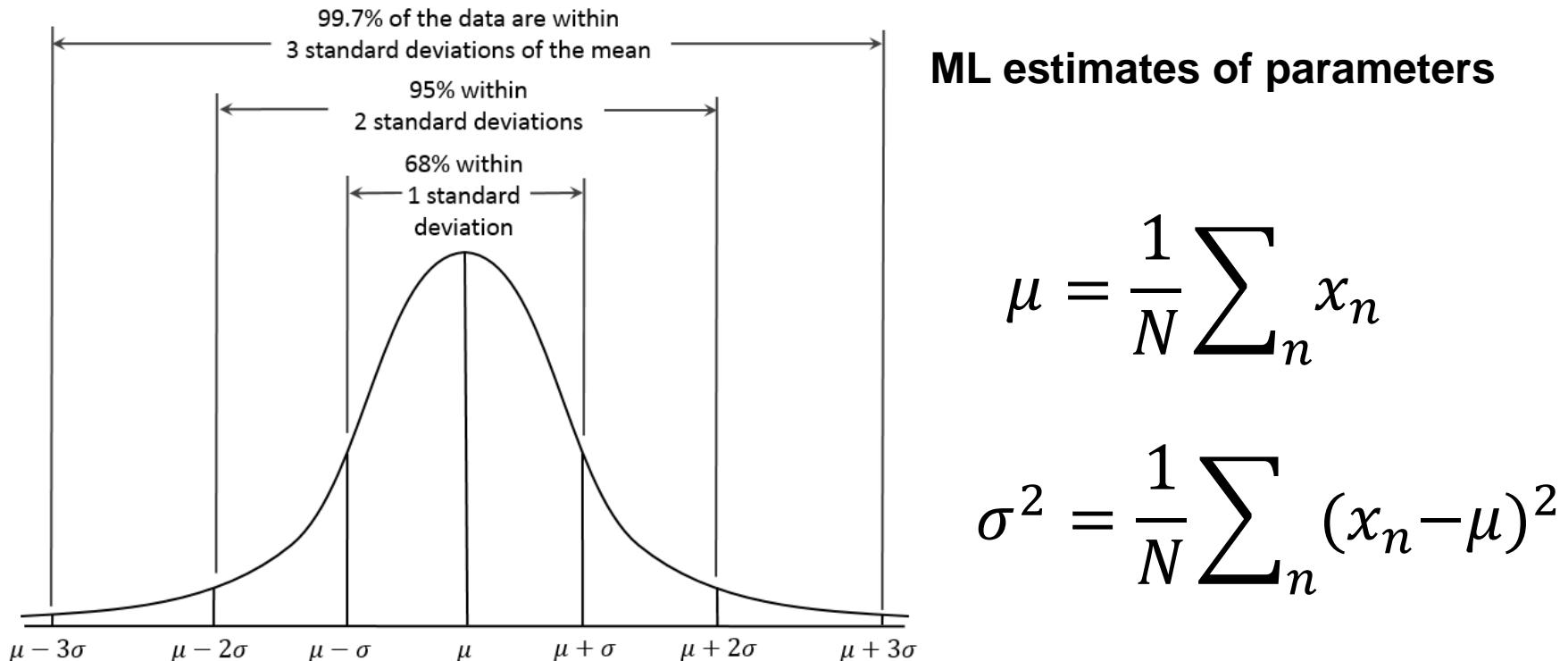
$$\begin{aligned} p(\boldsymbol{\pi}|\mathbf{X}) &= \frac{P(\mathbf{X}|\boldsymbol{\pi})p(\boldsymbol{\pi})}{P(\mathbf{X})} \propto \prod_c \pi_c^{m_c} \prod_c \pi_c^{\alpha_c - 1} \\ &= \prod_{c=1} \pi_c^{m_c + \alpha_c - 1} \propto \text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha} + \mathbf{m}) \end{aligned}$$

Sufficient statistics  $\mathbf{m} = [m_1, \dots, m_C]$ ,

- Using **Dirichlet as a prior for Categorical parameter  $\boldsymbol{\pi}$**  results in **Dirichlet posterior distribution** → **Dirichlet is conjugate prior to Categorical dist.**
- $\alpha_c - 1$  can be seen as a prior count for the individual events.

# Gaussian distribution (univariate)

$$p(x) = \mathcal{N}(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



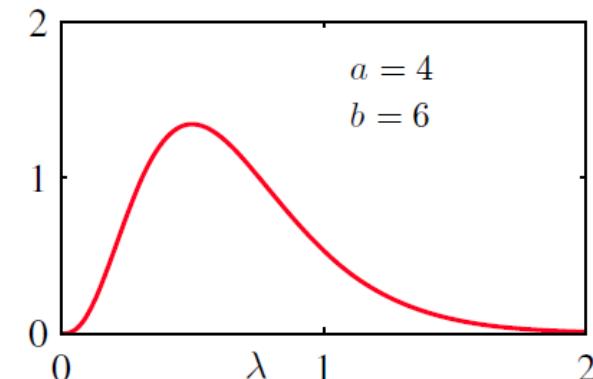
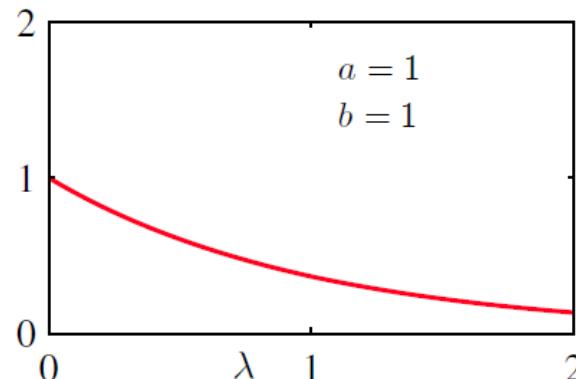
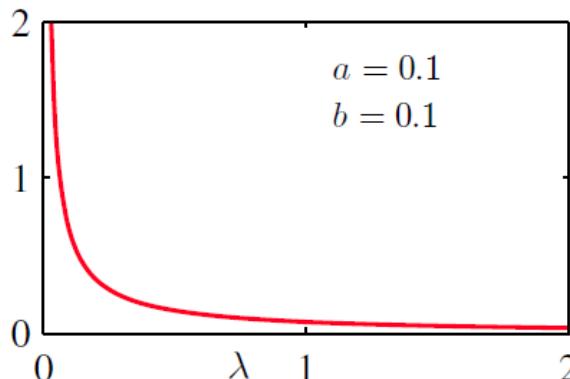
# Gamma distribution

Normal distribution can be expressed in terms of precision  $\lambda = \frac{1}{\sigma^2}$

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} = \sqrt{\frac{\lambda}{2\pi}} e^{-\frac{\lambda}{2}(x-\mu)^2}$$

$$\text{Gam}(\lambda|a, b) = \frac{1}{\Gamma(a)} b^a \lambda^{a-1} e^{-b\lambda}$$

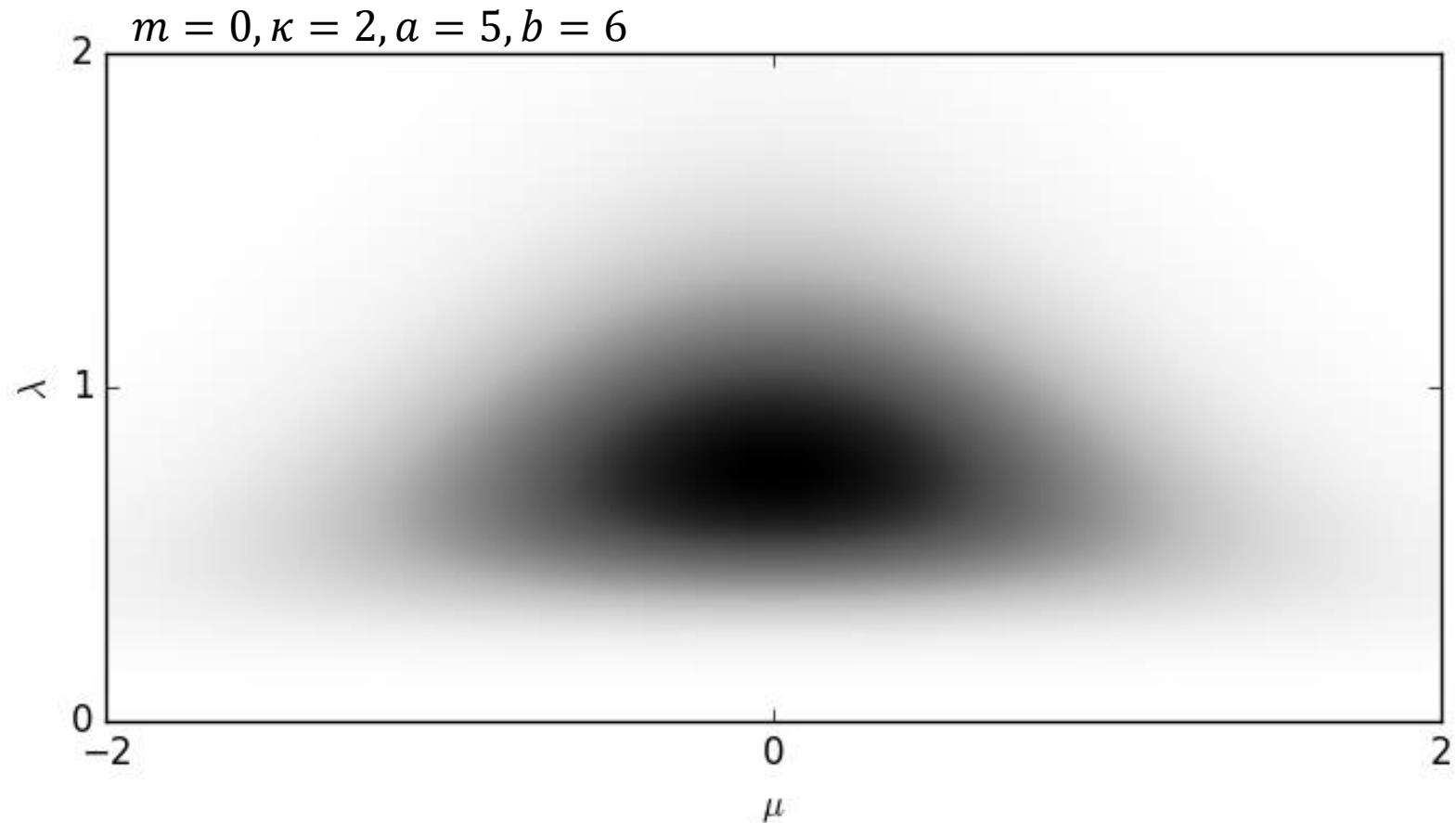
**Gamma distribution** defined for  $\lambda > 0$  can be used as a prior over the precision



# NormalGamma distribution

$$\text{NormalGama}(\mu, \lambda | m, \kappa, a, b) = \mathcal{N}(\mu | m, (\kappa\lambda)^{-1}) \text{Gam}(\lambda | a, b)$$

Joint distribution over  $\mu$  and  $\lambda$ . Note that  $\mu$  and  $\lambda$  are not independent.



# NormalGamma distribution

- **NormalGamma distribution** is the conjugate prior for Gaussian dist.
- Given observations  $\mathbf{x} = [x_1, x_2, x_3, \dots x_N]$ , the posterior distribution

$$\begin{aligned} p(\mu, \lambda | \mathbf{x}) &= \frac{p(\mathbf{x}|\mu, \lambda)p(\mu, \lambda)}{p(\mathbf{x})} \\ &\propto \prod_i \mathcal{N}(x_i; \mu, \sigma^2) \text{NormalGamma}(\mu, \lambda | \textcolor{teal}{m}, \textcolor{blue}{\kappa}, \textcolor{violet}{a}, \textcolor{red}{b}) \\ &\propto \text{NormalGamma}\left(\mu, \lambda \middle| \frac{\kappa m + N \bar{x}}{\kappa + N}, \textcolor{blue}{\kappa} + N, \textcolor{violet}{a} + \frac{N}{2}, \textcolor{red}{b} + \frac{N}{2} \left(s + \frac{\kappa(\bar{x} - m)^2}{\kappa + N}\right)\right) \end{aligned}$$

Defined in terms of sufficient statistics  $N$  and  $\bar{x} = \frac{1}{N} \sum_{n=1}^N x_n$        $s = \frac{1}{N} \sum_{n=1}^N (x_n - \bar{x})^2$

Note that the prior parameters can be interpreted as follows:

$\textcolor{violet}{a}$  - prior number of observation for precision (or variance)

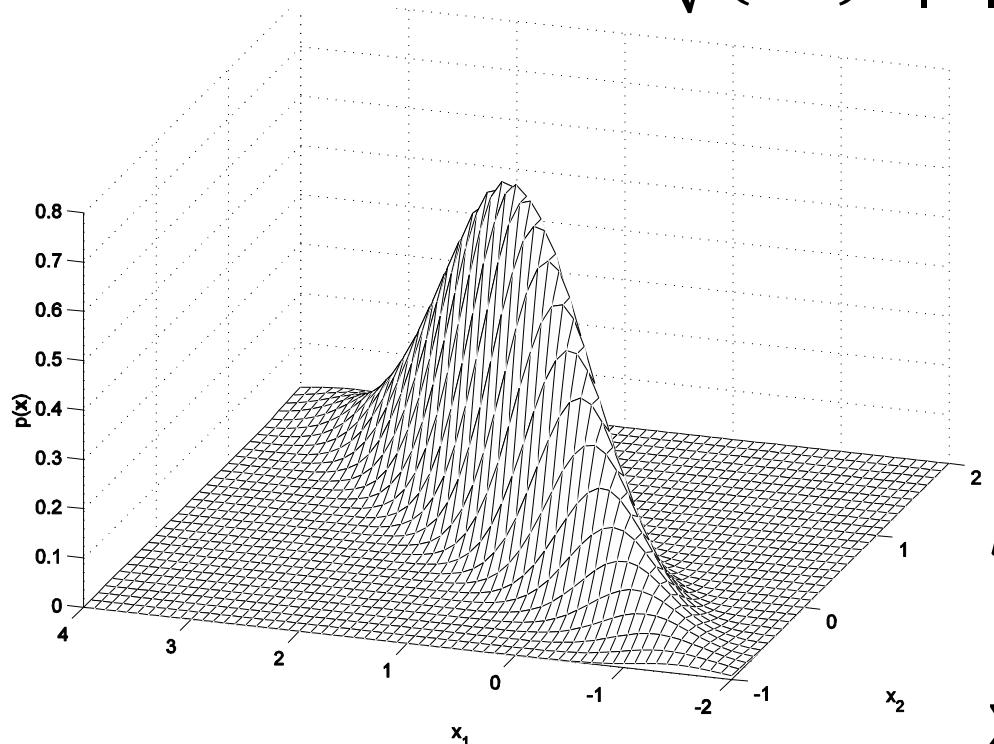
$\textcolor{red}{b}/\textcolor{violet}{a}$  - prior variance (around  $\textcolor{teal}{m}$ )

$\textcolor{blue}{\kappa}$  - number of prior observations for mean

$\textcolor{teal}{m}$  - prior mean

# Gaussian distribution (multivariate)

$$p(x_1, \dots, x_D) = \\ \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}-\boldsymbol{\mu})}$$



ML estimates of parameters

$$\boldsymbol{\mu} = \frac{1}{N} \sum_n \mathbf{x}_n$$

$$\boldsymbol{\Sigma} = \frac{1}{N} \sum_n (\mathbf{x}_n - \boldsymbol{\mu})(\mathbf{x}_n - \boldsymbol{\mu})^T$$

# Gaussian distribution (multivariate)

$$\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}-\boldsymbol{\mu})}$$

Conjugate prior is **Normal-Wishart**

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \boldsymbol{\mu}_0, \beta, \mathbf{W}, \nu) = \mathcal{N}(\boldsymbol{\mu} | \boldsymbol{\mu}_0, (\beta \boldsymbol{\Lambda})^{-1}) \mathcal{W}(\boldsymbol{\Lambda} | \mathbf{W}, \nu)$$

where

$$\mathcal{W}(\boldsymbol{\Lambda} | \mathbf{W}, \nu) = B |\boldsymbol{\Lambda}|^{(\nu - D - 1)/2} \exp\left(-\frac{1}{2} \text{Tr}(\mathbf{W}^{-1} \boldsymbol{\Lambda})\right)$$

is **Wishart distribution** and

$$\boldsymbol{\Lambda} = \boldsymbol{\Sigma}^{-1}$$

# Exponential family

- All the distributions described so far are distributions from the **exponential family**, which can be expressed in the following form

$$p(\mathbf{x}|\boldsymbol{\eta}) = h(\mathbf{x}) g(\boldsymbol{\eta}) \exp\{\boldsymbol{\eta}^T \mathbf{u}(\mathbf{x})\}$$

- For example, for Gaussian distribution:

$$\mathcal{N}(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{1}{2\sigma^2} x^2 + \frac{\mu}{\sigma^2} x - \frac{\mu^2}{2\sigma^2}\right\}$$

$$\boldsymbol{\eta} = \begin{pmatrix} \mu/\sigma^2 \\ -1/2\sigma^2 \end{pmatrix} \quad \mathbf{u}(x) = \begin{pmatrix} x \\ x^2 \end{pmatrix} \quad g(\boldsymbol{\eta}) = \sqrt{-\frac{2\eta_2}{2\pi}} \exp\left(\frac{\eta_1^2}{4\eta_2}\right) \quad h(x) = 1$$

- To evaluate likelihood of set of observations:

$$\prod_n \mathcal{N}(x_n; \mu, \sigma^2) = \exp\left\{-\frac{1}{2\sigma^2} \sum_n x_n^2 + \frac{\mu}{\sigma^2} \sum_n x_n - N \left( \frac{\mu^2}{2\sigma^2} + \frac{\log(2\pi\sigma^2)}{2} \right)\right\}$$

$$= g(\boldsymbol{\eta})^N \exp\left\{\boldsymbol{\eta}^T \sum_{n=1}^N \mathbf{u}(x_n)\right\} \prod_n h(x_n)$$

# Exponential family

For any distributions from exponential family

$$p(\mathbf{x}|\boldsymbol{\eta}) = h(\mathbf{x}) \, g(\boldsymbol{\eta}) \exp\{\boldsymbol{\eta}^T \mathbf{u}(\mathbf{x})\}$$

- Likelihood  $p(\mathbf{X}|\boldsymbol{\eta})$  of observed data  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N]$  can be evaluated using the sufficient statistics  $N$  and  $\sum_{n=1}^N \mathbf{u}(\mathbf{x}_n)$ :

$$p(\mathbf{X}|\boldsymbol{\eta}) = g(\boldsymbol{\eta})^N \exp\left\{\boldsymbol{\eta}^T \sum_{n=1}^N \mathbf{u}(x_n)\right\} \prod_n h(x_n)$$

- Conjugate prior distribution over parameter  $\boldsymbol{\eta}$  exists in form:

$$p(\boldsymbol{\eta}|\boldsymbol{\theta}, \nu) = f(\boldsymbol{\theta}, \nu) \, g(\boldsymbol{\eta})^\nu \exp\{\boldsymbol{\eta}^T \boldsymbol{\theta}\} = f(\boldsymbol{\theta}, \nu) \exp\left\{\begin{bmatrix} \nu \\ \boldsymbol{\theta} \end{bmatrix}^T \begin{bmatrix} \ln g(\boldsymbol{\eta}) \\ \boldsymbol{\eta} \end{bmatrix}\right\} = f(\boldsymbol{\theta}, \nu) \exp\{\boldsymbol{\theta}^T \mathbf{v}(\boldsymbol{\eta})\}$$

- Posterior distribution takes the same form as the conjugate prior, and we need only the prior parameters and the sufficient stats to evaluate it:

$$p(\boldsymbol{\eta}|\mathbf{X}) = p(\boldsymbol{\eta}|\boldsymbol{\theta} + \sum_{n=1}^N \mathbf{u}(x_n), \nu + N) \propto g(\boldsymbol{\eta})^{\nu+N} \exp\left\{\boldsymbol{\eta}^T \left(\boldsymbol{\theta} + \sum_{n=1}^N \mathbf{u}(x_n)\right)\right\}$$

- $\boldsymbol{\theta}/\nu$  can be seen as a prior observation and  $\nu$  as a prior count of observations

# Parameter estimation revisited

- Let's estimate again parameters  $\boldsymbol{\eta}$  of a chosen  $p(\mathbf{x}|\boldsymbol{\eta})$  distribution given some of observed data  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N]$
- Using the Bayes rule, we get the posterior distribution

$$p(\boldsymbol{\eta}|\mathbf{X}) = \frac{P(\mathbf{X}|\boldsymbol{\eta})p(\boldsymbol{\eta})}{P(\mathbf{X})}$$

- We can choose the most likelihood parameters: **Maximum a-posteriori (MAP)** estimate

$$\hat{\boldsymbol{\eta}}^{MAP} = \arg \max_{\boldsymbol{\eta}} p(\boldsymbol{\eta}|\mathbf{X}) = \arg \max_{\boldsymbol{\eta}} p(\mathbf{X}|\boldsymbol{\eta})p(\boldsymbol{\eta})$$

- Assuming flat (constant) prior  $p(\boldsymbol{\eta}) = const$ , we obtain **Maximum likelihood (ML)** estimate as a special case:

$$\hat{\boldsymbol{\eta}}^{ML} = \arg \max_{\boldsymbol{\eta}} P(\mathbf{X}|\boldsymbol{\eta})$$

# Posterior predictive distribution

- We do not need to obtain a point estimate of the parameters  $\hat{\boldsymbol{\eta}}$
- It is always good to postpone making hard decisions
- Instead, we can take into account the uncertainty encoded in the posterior distribution  $p(\boldsymbol{\eta}|\mathbf{X})$  when evaluating **posterior predictive probability** for a new data point  $x'$  (as we did in our coin flipping example)

$$p(x'|\mathbf{X}) = \int p(x', \boldsymbol{\eta}|\mathbf{X}) d\boldsymbol{\eta} = \int p(x'|\boldsymbol{\eta})p(\boldsymbol{\eta}|\mathbf{X}) d\boldsymbol{\eta}$$

- Rather than using one most likely setting of parameters  $\hat{\boldsymbol{\eta}}$ , we average over their different setting, which could possibly generate the observed data  $\mathbf{X}$   
→ this approach is robust to overfitting

# Posterior predictive for Bernoulli

- Beta prior on parameters of Bernoulli distribution leads to Beta posterior

$$\begin{aligned} p(\mu|\mathbf{x}) &\propto \prod_n \text{Bern}(x_n|\mu) \text{Beta}(\mu|a_0, b_0) \propto \text{Beta}(\mu|a_0 + H, b_0 + T) \\ &= \text{Beta}(\mu|a_N, b_N) \end{aligned}$$

- The posterior predictive distribution is again Bernoulli

$$\begin{aligned} p(x'|\mathbf{x}) &= \int p(x'|\mu)p(\mu|\mathbf{x}) d\mu = \int \text{Bern}(x'|\mu)\text{Beta}(\mu|a_N, b_N) d\mu \\ &= \text{Bern}\left(x' \middle| \frac{a_N}{a_N + b_N}\right) = \text{Bern}\left(x' \middle| \frac{a_0 + H}{a_0 + b_0 + N}\right) \end{aligned}$$

- In our coin flipping example:

$$p(\mu) = \mathcal{U}(0,1) = \text{Beta}(\mu|a_0, b_0) = \text{Beta}(\mu|1,1)$$

$$p(\mu|\mathbf{x}) = \text{Beta}(\mu|a_N, b_N) = \text{Beta}(\mu|a_0 + H, b_0 + T) = \text{Beta}(\mu|1 + 750, 1 + 250)$$

$$p(x'|\mathbf{x}) = \text{Bern}\left(x' \middle| \frac{a_N}{a_N + b_N}\right) = 751/1002 = 0.7495$$

# Posterior predictive for Categorical

- Dirichlet prior on parameters of Categorical distribution leads to Dirichlet posterior

$$p(\boldsymbol{\pi}|\mathbf{X}) \propto \prod_n \text{Cat}(\mathbf{x}_n|\boldsymbol{\pi}) \text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_0) \propto \text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_0 + \mathbf{m}) = \text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_N)$$

- The posterior predictive distribution is again Categorical

$$\begin{aligned} p(\mathbf{x}'|\mathbf{X}) &= \int p(\mathbf{x}'|\boldsymbol{\pi})p(\boldsymbol{\pi}|\mathbf{X}) d\boldsymbol{\pi} = \int \text{Cat}(\mathbf{x}'|\boldsymbol{\pi})\text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_N) d\boldsymbol{\pi} \\ &= \text{Cat}\left(\mathbf{x}' \middle| \frac{\boldsymbol{\alpha}_N}{\sum_c \alpha_{Nc}}\right) = \text{Cat}\left(\mathbf{x}' \middle| \frac{\boldsymbol{\alpha}_0 + \mathbf{m}}{\sum_c \alpha_{0c} + m_c}\right) \end{aligned}$$

# Student's t-distribution

- NormalGamma prior on parameters of Gaussian distribution leads to NormalGamma posterior

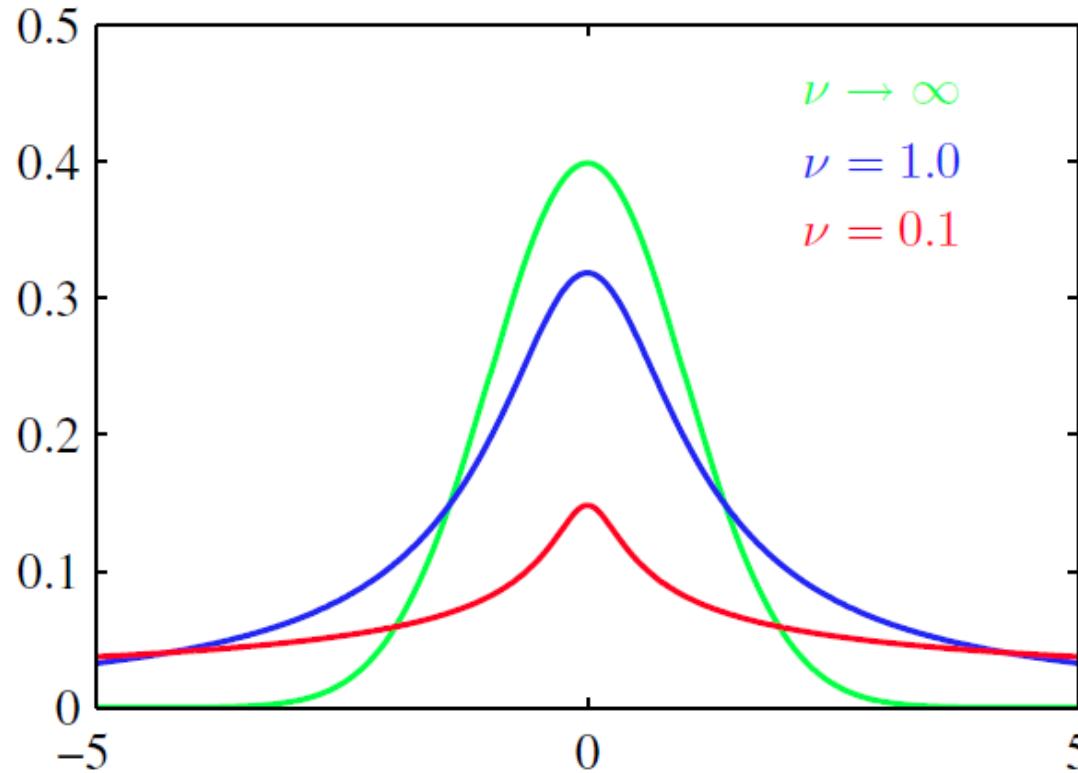
$$\begin{aligned} p(\mu, \lambda | \mathbf{x}) &\propto \prod_i \mathcal{N}(x_i; \mu, \sigma^2) \text{NormalGamma}(\mu, \lambda | m_0, \kappa_0, a_0, b_0) \\ &\propto \text{NormalGamma}\left(\mu, \lambda \left| \frac{\kappa_0 m_0 + N \bar{x}}{\kappa_0 + N}, \kappa_0 + N, a_0 + \frac{N}{2}, b_0 + \frac{N}{2} \left( s + \frac{\kappa_0 (\bar{x} - m_0)^2}{\kappa_0 + N} \right) \right.\right) \\ &= \text{NormalGamma}(\mu, \lambda | m_N, \kappa_N, a_N, b_N) \end{aligned}$$

- The posterior predictive distribution is Student's t-distribution

$$\begin{aligned} p(\mathbf{x}' | \mathbf{x}) &= \iint p(x' | \mu, \lambda) p(\mu, \lambda | \mathbf{x}) d\mu d\lambda \\ &= \iint \mathcal{N}(x' | \mu, \lambda^{-1}) \text{NormalGamma}(\mu, \lambda | m_N, \kappa_N, a_N, b_N) d\mu d\lambda \\ &= \text{St}\left(x' | m_N, 2a_N, \frac{a_N \kappa_N}{b_N (\kappa_N + 1)}\right) \end{aligned}$$

# Student's t-distribution

$$\text{St}(x | \mu, \nu, \gamma) = \frac{\Gamma\left(\frac{\nu}{2} + \frac{1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \left(\frac{\gamma}{\pi\nu}\right)^{\frac{1}{2}} \left[1 + \frac{\gamma(x - \mu)^2}{\nu}\right]^{-\frac{\nu}{2} - \frac{1}{2}}$$



- Gaussian distribution is a special case of Student's with degree of freedom  $\nu \rightarrow \infty$
- For the posterior  $p(\mu, \lambda | \mathbf{x})$ ,  $\nu = 2a_N = 2a_0 + N$