

Přítelka:

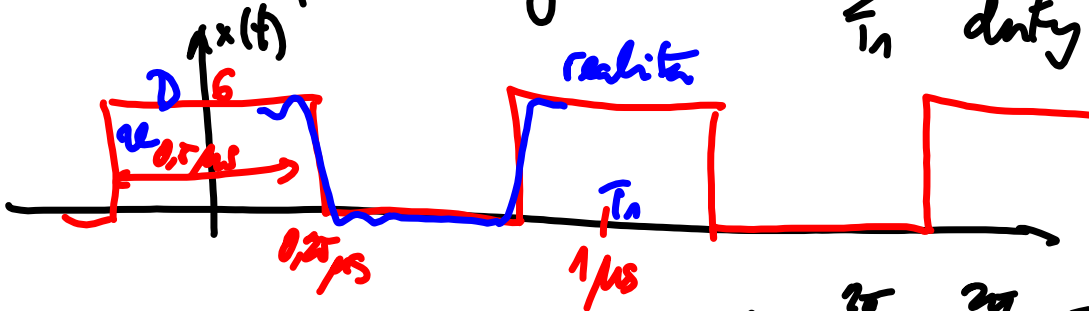
stř. 3.11. 9^h5

pa. 5.11. 15^h5

| COVID danger!

FR - posun signálu

$\omega \leq \omega_1$ střída
dní cycle



$$\omega_1 = \frac{2\pi}{T_n} = \frac{2\pi}{1 \cdot 10^{-6}} = 2\pi \cdot 10^6$$

$$c_k = \frac{D_0}{T_n} \text{sinc}\left(\frac{\omega}{2} k \omega_1\right)$$

parn. funkce pro obecnou

$$\omega: \text{sinc}\left(\frac{\omega}{2}\right)$$

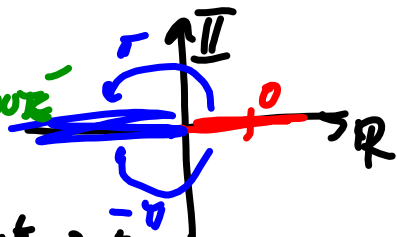
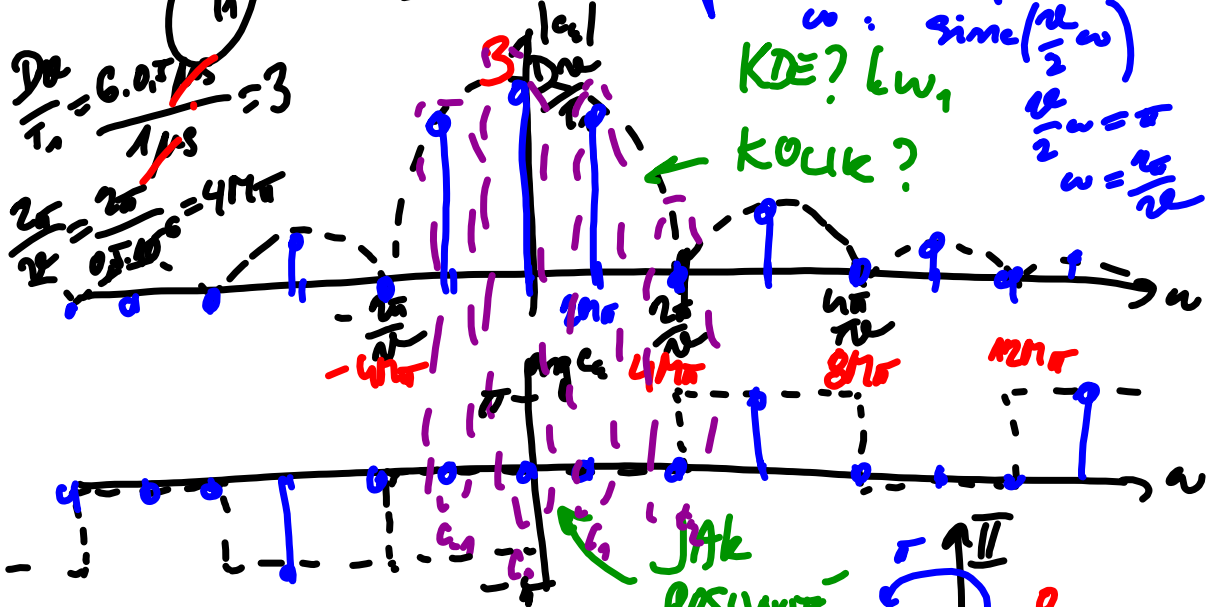
KDE? $k\omega_1$

KOLIK?

$$\frac{\omega}{2} = \pi \implies \omega = \frac{2\pi}{2}$$

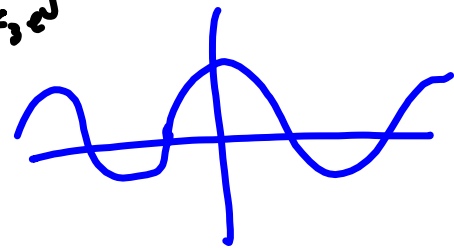
$$\frac{D_0}{T_n} = \frac{0.075 \mu\text{s}}{1 \mu\text{s}} = 3$$

$$\frac{2\pi}{2} = \frac{2\pi}{0.5 \cdot 10^6} = 4\pi \cdot 10^6$$



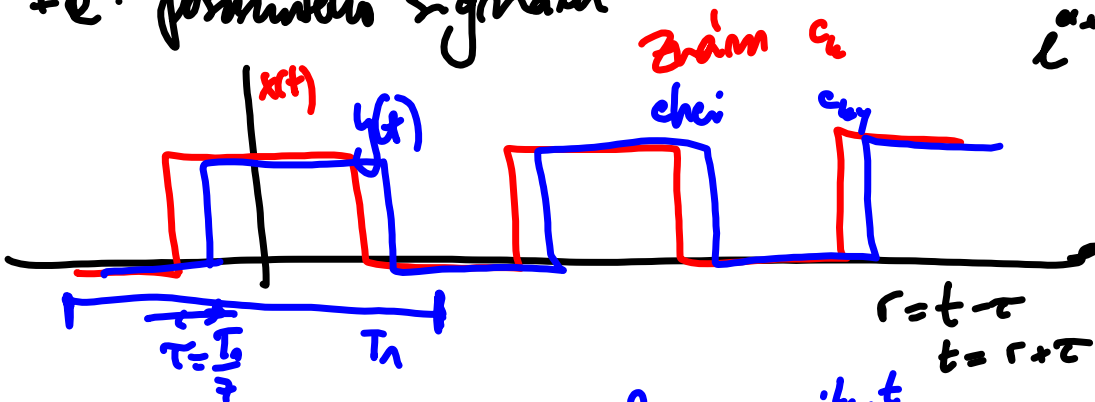
$$x(t) = c_0 e^{j0t} + \cancel{c_1 e^{j\omega_1 t}} + c_2 e^{j2\omega_1 t} + c_0 + \cancel{c_1 e^{-j\omega_1 t}} + \cancel{c_2 e^{-j2\omega_1 t}}$$

$c_2 = 0$ $c_1 = 0$



$F\{e\}$ posunutého signálu

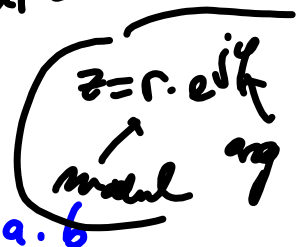
$e^{a+b} = e^a \cdot e^b$



$$c_y = \frac{1}{T_n} \int_{T_n} y(t) e^{j k \omega t} dt = \frac{1}{T_n} \int_{T_n} x(t - \tau) e^{j k \omega t} dt =$$

$$= \frac{1}{T_n} \int_{T_n} x(r) e^{j k \omega (r + \tau)} dr = \frac{1}{T_n} \int_{T_n} x(r) e^{j k \omega r} (e^{j k \omega \tau}) dr =$$

$$= e^{j k \omega \tau} \left(\frac{1}{T_n} \int_{T_n} x(r) e^{j k \omega r} dr \right) = e^{j k \omega \tau} \cdot c_x$$



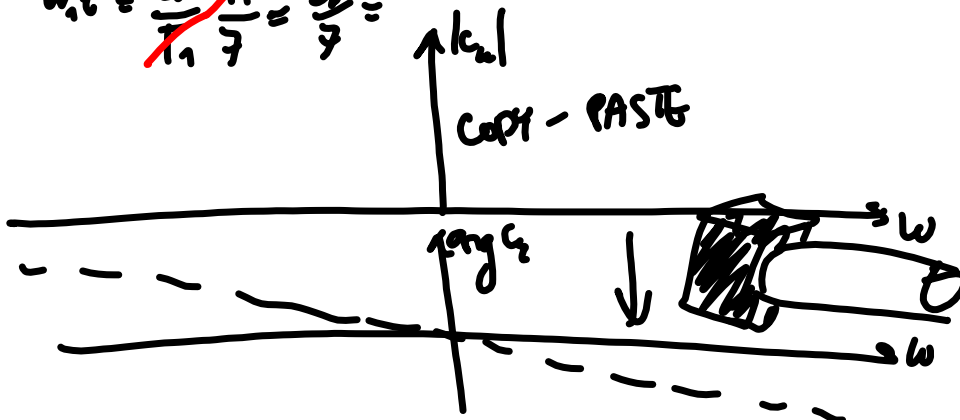
$k_{ny} = |e^{j k \omega \tau}| |c_x| = |c_x|$ *moduly existenci stejne!*

$|k b| = |a| |b|$

$arg c_y = arg(e^{j k \omega \tau}) + arg c_x = -k \omega \tau + arg c_x$
konstanta!

$arg a b = arg a + arg b$

$\omega_c \tau = \frac{2\pi}{T_n} \frac{T_n}{7} = \frac{2\pi}{7}$



SHRNUTI F.Ř.

vstup: periodický signál se spoj.ým časem.

výstup: koeficienty c_k F. řady ← "Spektrum"

lede? $k \omega_0$, kde $\omega_0 = \frac{2\pi}{T}$

kelte? $|c_k|$

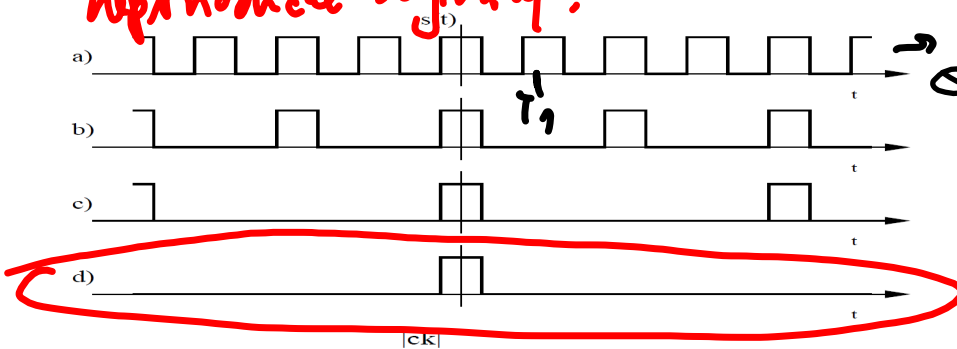
jaka posunuti? $\arg c_k$

zpětný signál: $|c_k|$ - cap - paste
 $\arg c_k$ "sjiždějí" \Rightarrow kapacita

synléza: vždy s páry koeficientů c_k a c_{-k}

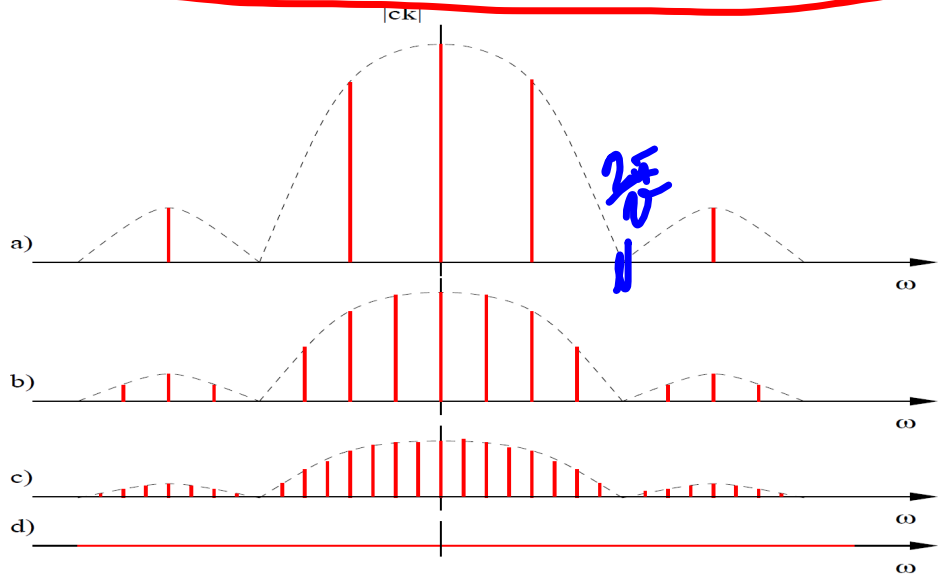
Fourierova transformace F.T.

neperiodické signály!



F.T.

$$C_k = \frac{1}{T_1} \int_{T_1} x(t) e^{-j k \omega t} dt$$



How TO HACK F.Ď. aby pracovala s
kperiodickými signály.

$$c_k = \frac{1}{T_1} \int_{-\frac{T_1}{2}}^{\frac{T_1}{2}} x(t) e^{j\omega_k t} dt$$

$$T_1 \rightarrow \infty$$

$$\frac{1}{T_1} = \frac{\omega_n}{2\pi}$$

$$\omega_n = \frac{2\pi}{T_1} \rightarrow d\omega \quad \frac{1}{T_1} = \frac{d\omega}{2\pi}$$

$$dc = \frac{d\omega}{2\pi} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

ω - libovolná
kružová frekvence
která neexistuje!

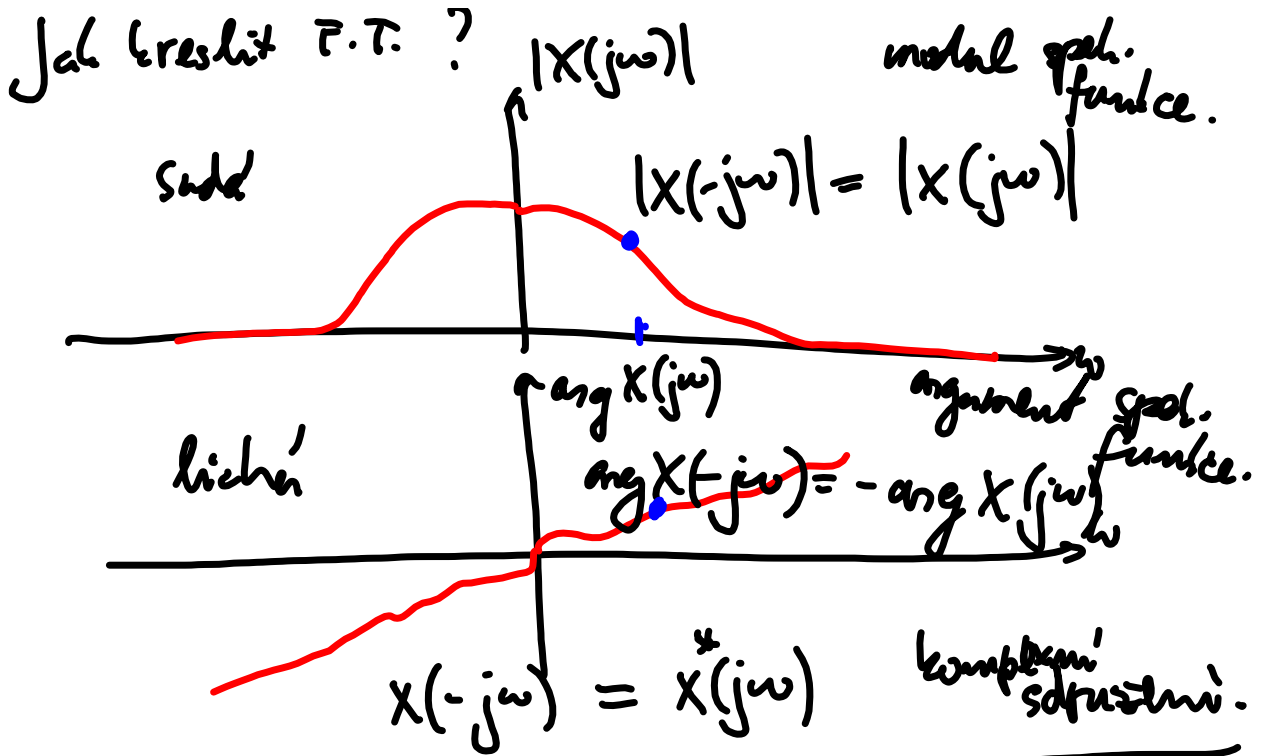
$$c_k \rightarrow dc$$

$$\frac{2\pi dc}{d\omega} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

Spektrální funkce

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

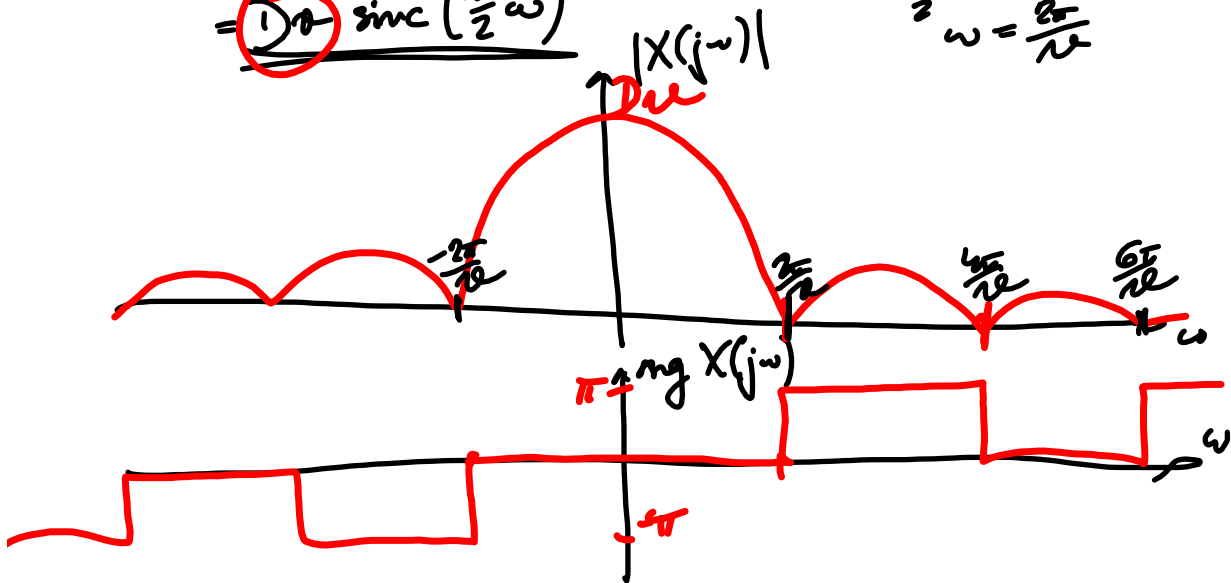
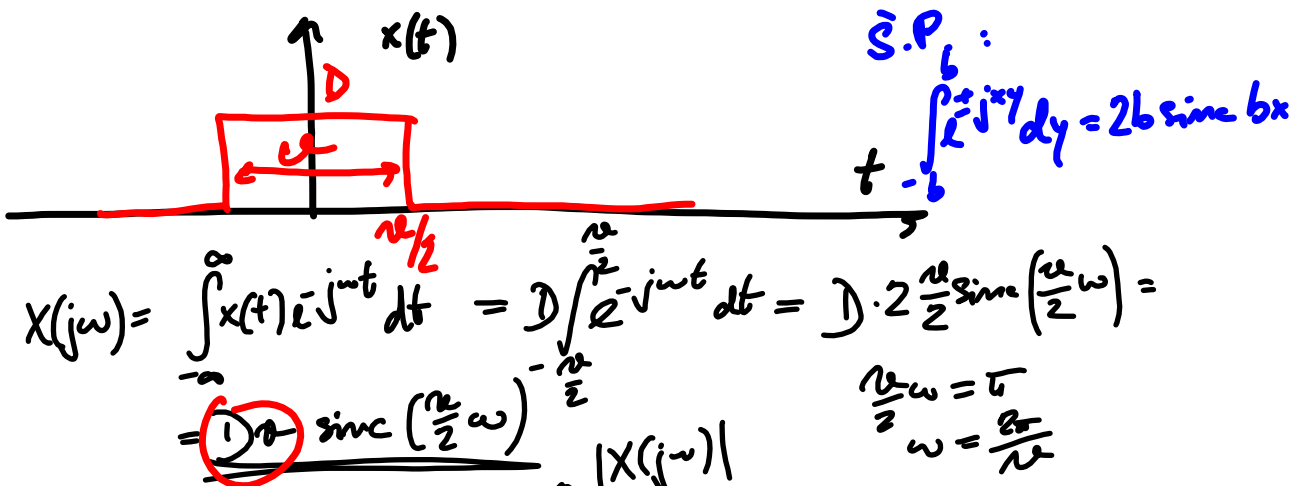
F.Ď.
j ω ?
souvislost
s Laplaceovou transf.
TĎD lath.

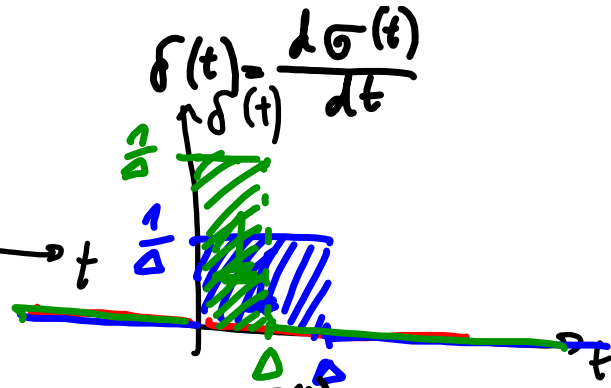
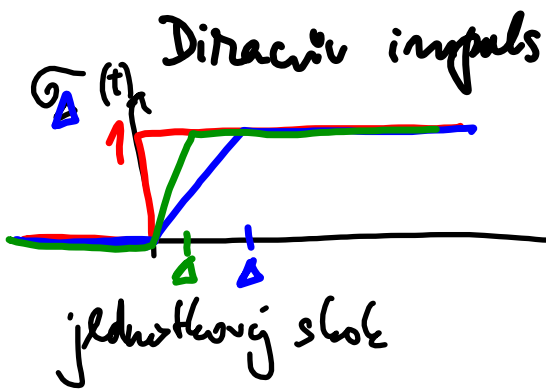


výstup = měna, říjcha, konstanta Sum. operátor vstup $j\omega$ čas frekvence

F.T.: $X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$ \leftrightarrow F.R. $c_k = \frac{1}{T_1} \int_{T_1} x(t) e^{-j\omega t} dt$

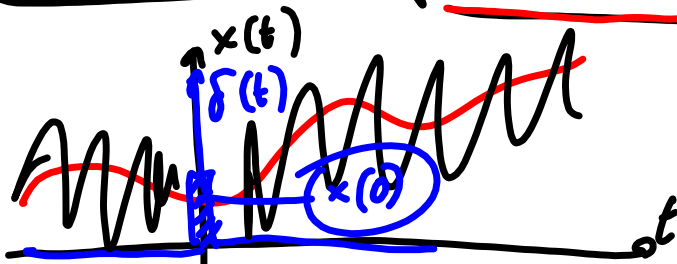
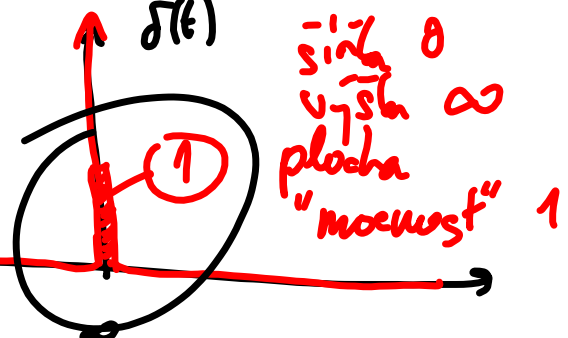
I.F.T.: $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{+j\omega t} d\omega$ \leftrightarrow I.F.R. $x(t) = \sum_{k=-\infty}^{\infty} c_k e^{+j\omega t}$



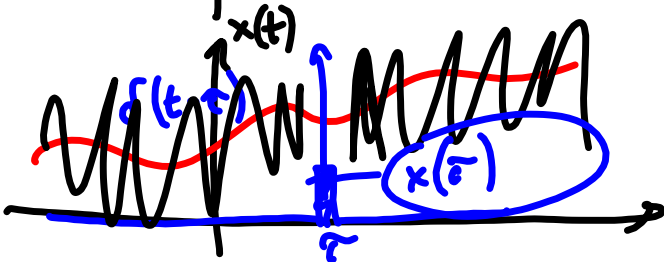


$$\frac{1}{\Delta t}$$

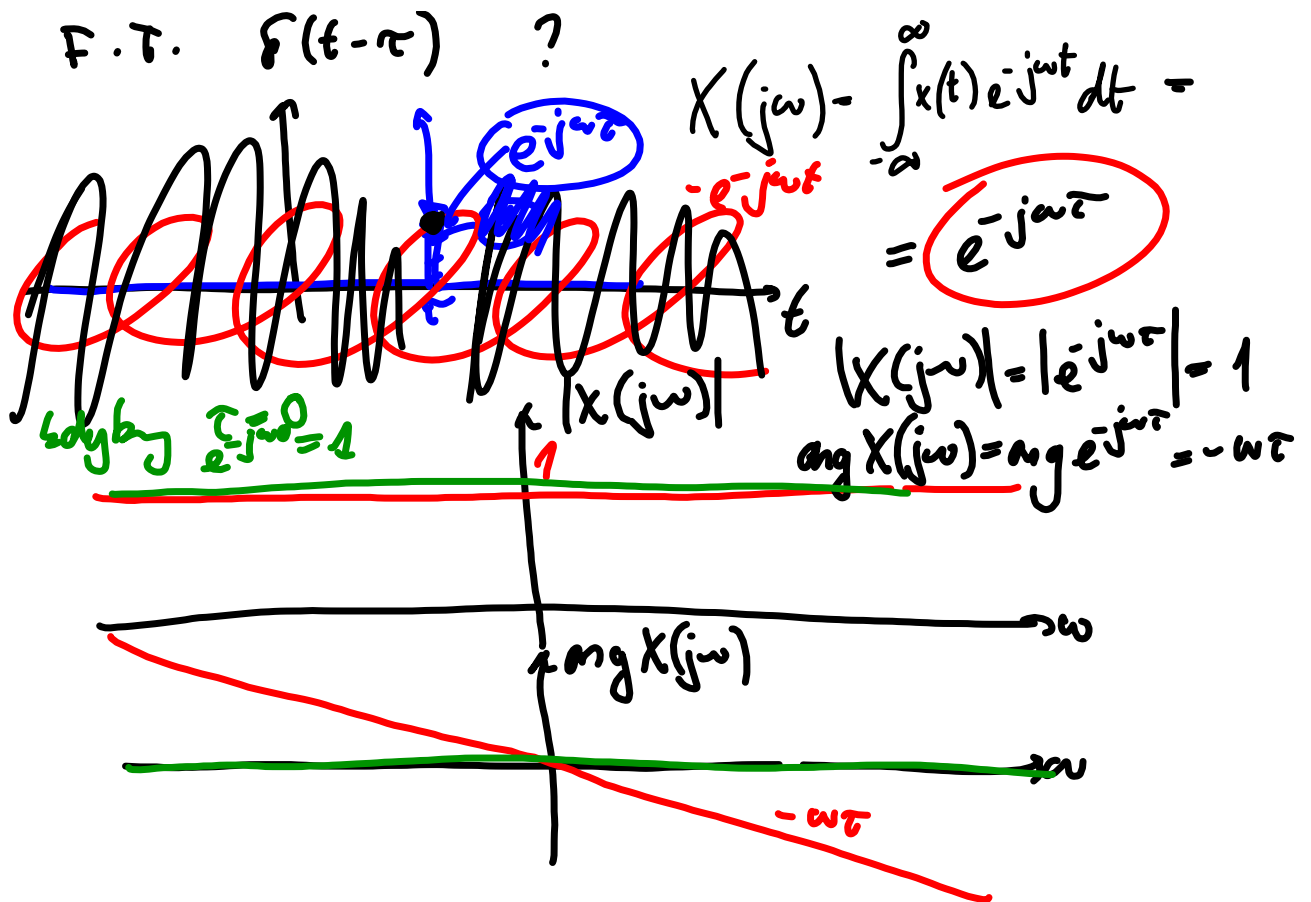
vzorovací schopnost



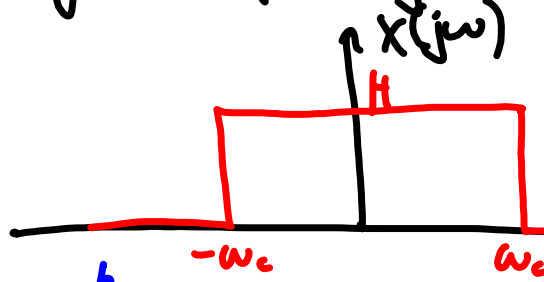
$$\int_{-\infty}^{\infty} x(t) \delta(t) dt = x(0)$$



$$\int_{-\infty}^{\infty} x(t) \delta(t-\tau) dt = x(\tau)$$



Signál odpovídá její obdélníkovému spektru

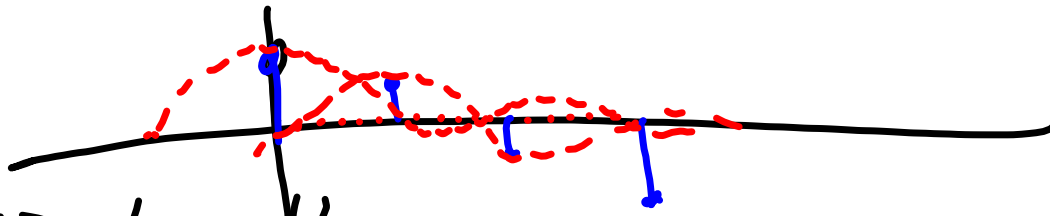
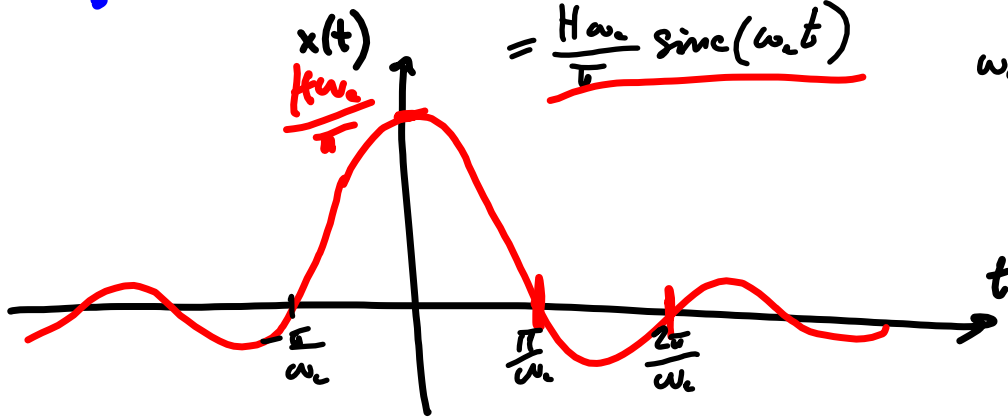


IFT: $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{+j\omega t} d\omega =$
 $= \frac{1}{2\pi} H \int_{-\omega_c}^{\omega_c} e^{j\omega t} d\omega =$

3.p. $\int_{-b}^b e^{\pm jxy} dy = 2b \operatorname{sinc} bx$

$= \frac{H}{2\pi} 2\omega_c \operatorname{sinc}(\omega_c t) =$
 $= \frac{H\omega_c}{\pi} \operatorname{sinc}(\omega_c t)$

$\omega_c t = \frac{\pi}{b}$
 $t = \frac{\pi}{\omega_c b}$



F.T. shrnutí:

vstup: nepřerodický signál se spoj. časem.

výstup: spektrální hustota $X(j\omega)$

kde?
kde?

všude
 $|X(j\omega)|$

jak posunuté? $\arg X(j\omega)$

$X(-j\omega) = X^*(j\omega)$

$x(t) \rightarrow X(j\omega)$

$x(t - \tau) \rightarrow X(j\omega) \cdot e^{-j\omega\tau}$

moduly se rozměří
(copy - paste)
argumenty $-\omega\tau$

Systemy
časová invariabilita $x(t) \rightarrow y(t)$
 $x(t - \tau) \rightarrow y(t - \tau)$

linearita $x_1(t) \rightarrow y_1(t)$
 $x_2(t) \rightarrow y_2(t)$
 $ax_1(t) + bx_2(t) \rightarrow ay_1(t) + by_2(t)$

konzalita $\left. \begin{array}{l} x(t) \\ x(\tau < t) \\ y(\tau < t) \end{array} \right\} \rightarrow y(t)$

Stabilita "bounded input \rightarrow bounded output"

$$x(t) \in \langle -B, B \rangle$$

izváno

$$y(t) \in \langle -C, C \rangle$$

može vyjít \rightarrow sfabily
 $\infty \rightarrow$ nestabilní.